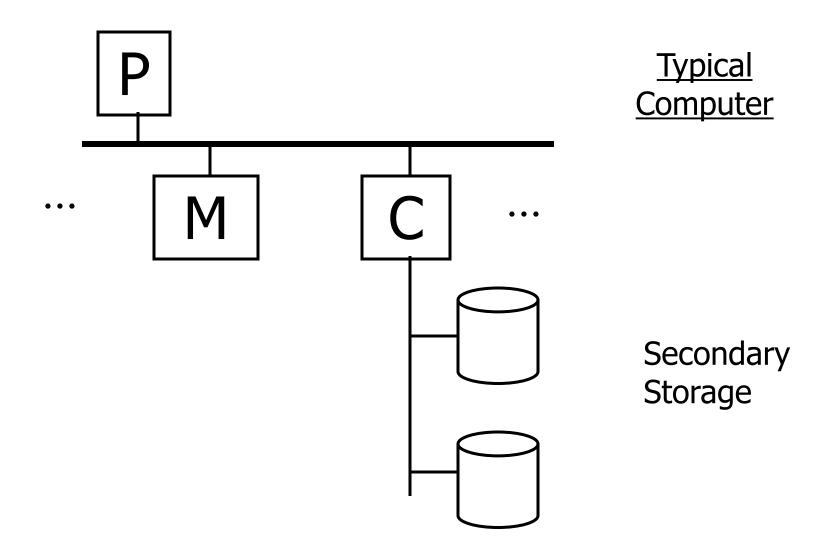
Hardware

Read Chap. 4 Riguzzi et al. Sistemi Informativi

Slides derived from those by Hector Garcia-Molina Some images by Wikipedia

<u>Outline</u>

- Hardware: Disks
- Access Times
- Reliability
- RAID



Processor

Fast, slow, reduced instruction set, with cache, pipelined...

Speed: 10,000→ 100,000 MIPS

<u>Memory</u>

Fast, slow, non-volatile, read-only,... Access time: $10^{\text{-}6} \rightarrow 10^{\text{-}9}$ sec. $1~\mu\text{s} \rightarrow 1~\text{ns}$

Secondary storage Hard Disks Tertiary storage Optical disks:

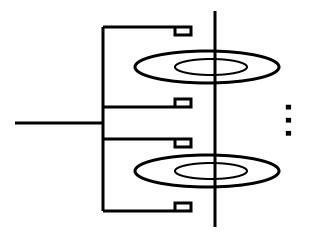
- CD-ROM
- •DVD-ROM...

Tape

Cartridges

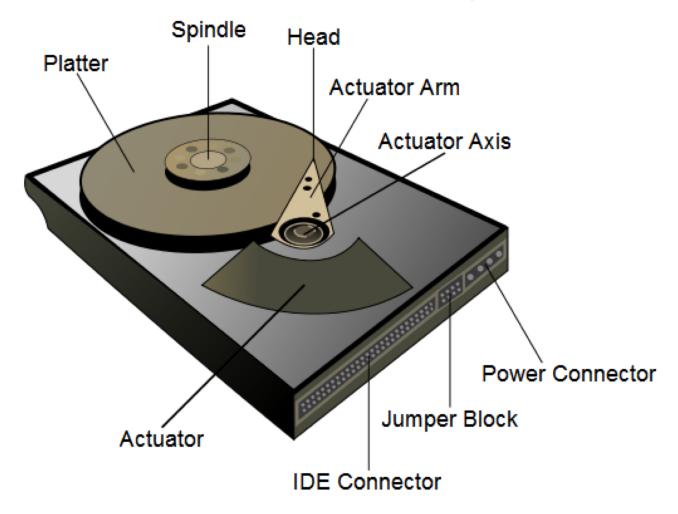
Robots

Focus on: "Typical Disk"

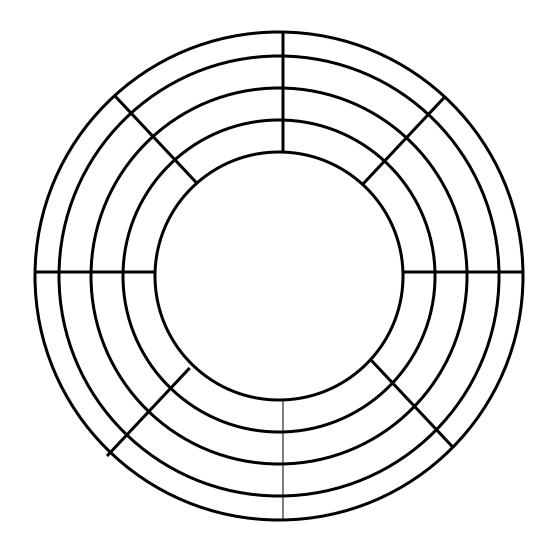


Terms: Platter, Surface, Head, Actuator Cylinder, Track Sector (physical), Block (logical), Gap

Disk Architecture



Top View



"Typical" Numbers

Diameter: 1.8, 2.5 or 3.5 inches

(1 inch=2.54 cm)

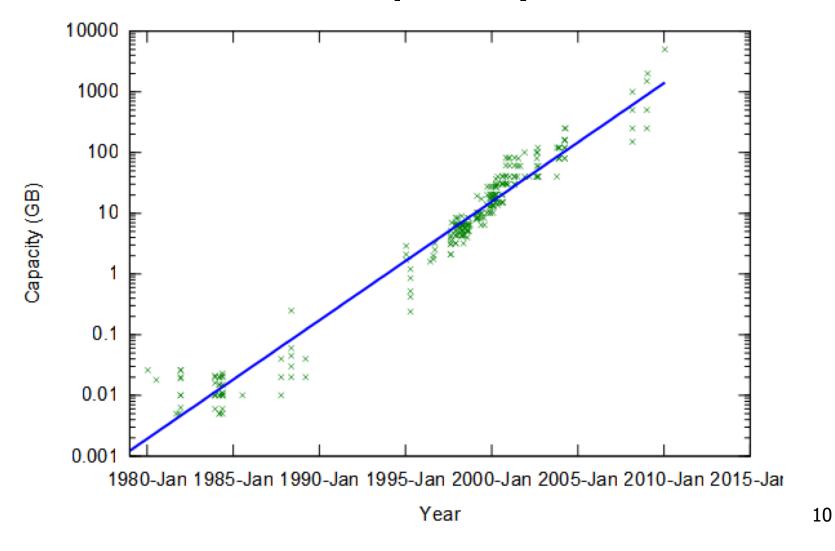
Cylinders: $10000 \rightarrow 50000$

Platters: 2 -> 7

Sector Size: $512B \rightarrow 50KB$

Capacity: $72 \text{ GB} \rightarrow 6\text{TB}$

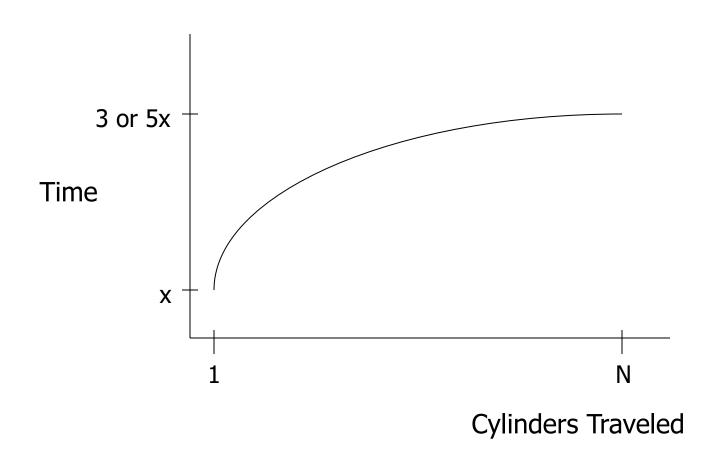
Capacity



Disk Access Time

Time = Seek Time +
Rotational Delay +
Transfer Time +
Other

Seek Time



Average Random Seek Time

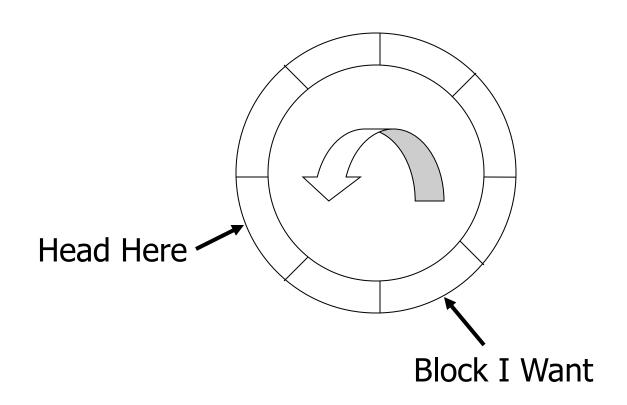
$$S = \frac{\sum\limits_{i=1}^{N}\sum\limits_{\substack{j=1\\j\neq i}}^{N}\text{SEEKTIME (i}\rightarrow j)}{N(N-1)}$$

"Typical" S: 3 ms \rightarrow 10 ms

Seek time

- Average seek time ranges from under 4 ms for high-end server drives to 15 ms for mobile drives
- For the most common mobile drives si about 12 ms
- For the most common desktop drives is about 9 ms.

Rotational Delay



Average Rotational Delay

```
R = 1/2 revolution
```

```
"typical" R = 4.17 ms (7200 RPM)
R=3 ms (10000 RPM)
R=2 ms (15000 RPM)
```

Transfer Time

 transfer time: revolution/n. blocks per track

Other Delays

- CPU time to issue I/O
- Contention for controller
- Contention for bus, memory

"Typical" Value: 0

- So far: Random Block Access
- What about: Reading "Next" block?

Time to get block = revolution/blocks

Cost for Writing similar to Reading

.... unless we want to verify!
need to add (full) rotation +
revolution/blocks

To <u>Modify</u> a Block?

To Modify Block:

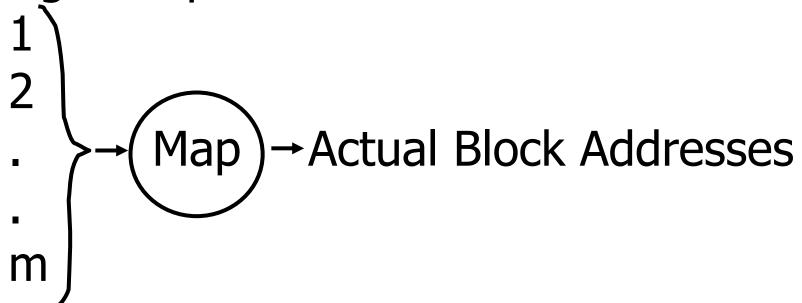
- (a) Read Block
- (b) Modify in Memory
- (c) Write Block
- [(d) Verify?]

Block Address:

- Physical Device
- Cylinder (Track) #
- Surface #
- Sector

Complication: Bad Blocks

- Messy to handle
- Map via software from integer sequence



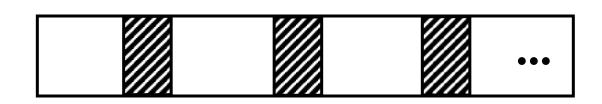
An Example

Megatron 747 Disk

- 3.5 in diameter
- 8 platters, 16 surfaces
- -2^{14} =16,384 tracks per surface (16,384 cylinders)
- $-2^7=128$ sectors per track
- -2^{12} =4096 bytes per sector
- Capacity
 - Disk= $2^{4*}2^{14*}2^{7*}2^{12}=2^{37}=128GB$
 - Single track= $2^{7*}2^{12}=512KB$
- Rotation speed: 7200 RPM
- Average seek time: 8.5 ms

7200 RPM \rightarrow 120 revolutions / sec \rightarrow 1 rev. = 8.33 msec.

One track:



Time over useful data:(8.33)(0.9)=7.5 ms. Time over gaps: (8.33)(0.1) = 0.833 ms. Transfer time 1 sector = 7.5/128=0.059 ms. Trans. time 1 sector+gap=8.33/128=0.065ms.

Burst Bandwith

4 KB in 0.059 ms.

BB = 4/0.059 = 68 KB/ms.

or

BB = 68 KB/ms x 1000 ms/1sec
x 1MB/1024KB
=
$$68,000/1024 = 66.4$$
 MB/sec

Sustained bandwith (over track) 512 KB in 8.33 ms.

$$SB = 512/8.33 = 61.5 \text{ KB/ms}$$

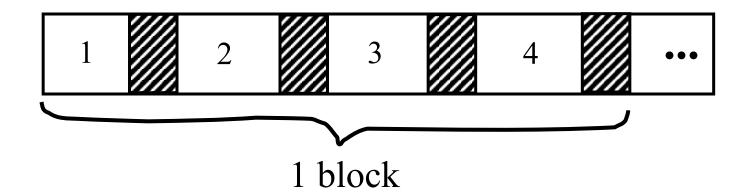
or

 $SB = 61.5 \times 1000/1024 = 60 MB/sec.$

 T_1 = Time to read one random block

 T_1 = seek + rotational delay + TT = 8.5 + (8.33/2) + 0.059 = 12.72 ms.

Suppose OS deals with 16 KB blocks



$$T_4 = 8.5 + (8.33/2) + 0.059*1 + (0.065)$$
* 3 = 12.92 ms

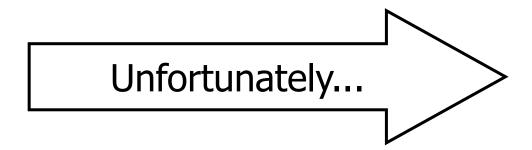
[Compare to $T_1 = 12.72$ ms]

 T_T = Time to read a full track (start at any block) $T_T = 8.5 + (0.065/2) + 8.33^* = 16.86 \text{ ms}$ to get to first block

* Actually, a bit less; do not have to read last gap.

Block Size Selection?

Big Block → Amortize I/O Cost



Big Block ⇒ Read in more useless stuff!
 and takes longer to read
 waste of space

Reliability

- Measured by the Mean Time to Failure (MTTF):
 - Length of time by which 50% of a population of disks will have failed catastrophically (head crash, no longer readable)
 - For modern disks, the MTTF is 10 years
 - This means that, on average, after 10 years it will crash
 - We can assume that every year 5% of the disks fail (uniform distribution assumption)
 - Probability that a disk fails in one year $P_F = 5\% = 1/20$

Disk Arrays

- Redundant Arrays of Inexpensive Disks (RAID)
- Two aims: increase speed and reliability

- Uses "block level striping"
 - Blocks that are consecutive for the OS are distributed evenly across different disks

RAID 0

A1 A2 consecutive blocks: A1-A8

A3 A4

A5 A6

A7 A8

- Improves reading and writing speed
 - With two disks, two blocks can be read at the same time
 - A request for block "A1" would be serviced by disk 1. A simultaneous request for block A3 would have to wait, but a request for A2 could be serviced concurrently
- Reduces reliability: if one disk fails, the data is lost.

- Creates an exact copy (or mirror) of a set of data on two or more disks.
- Typically, a RAID 1 array contains two disks
- Improved
 - Reading speed: two blocks can be read at the same time
 - Reliability: if disk 1 crashes, we can use disk 2.
 We lose the data only if disk 2 crashes while we are changing disk 1 (which can be done in ~3 h)
- Writing speed remains the same

RAID 1 A1 A1

A2 A2

A3 A3

A4 A4

 Uses block-level striping with a dedicated parity disk.

RAID 4

A1 A2 A3 Ap

B1 B2 B3 Bp

C1 C2 C3 Cp

D1 D2 D3 Dp

Consecutive blocks

A1-A3,B1-B3,

C1-C3, D1-D3

Parity block

- Bit i of the block in position j on the parity disk is the parity bit of the bits in position i in the blocks in position j in the other disks
- Eg., blocks of one byte, blocks A1-A3

Disk1 11110000

Disk2 10101010

<u>Disk3 00111000</u>

Disk4 01100010 (parity disk)

- Improves reading time: multiple blocks can be read at the same time
- Improves reliability: if one disk fails, we can reconstruct its content (assuming the others are correct)

• Problem:

- When writing a block, we need to read and write the parity disk's block
- This creates a bottleneck

 Uses block-level striping with parity data distributed across all member disks.

RAID 5

A1 A2 A3 Ap

B1 B2 Bp B3

C1 Cp C2 C3

Dp D1 D2 D3

- Reading and reliability as RAID 4
- Writing improved because the parity blocks are not all on one disk